

D-80N Intelligent Black Light Full-Color Night Vision Spherical Gimbal Camera



Characteristics

- 40x hybrid zoom camera, combined with the ultra-starlight image sensor and AIISP full color night vision imaging engine, can present clear fullcolor images in extremely low light environments, delivering night vision-level lowlight imaging experience. The D-80N also features superior HDR capability, ensuring both highlights and shadow details remain clearly visible even in complex lighting environments with strong contrast between bright and dark areas.
- NIR Laser lighting module ensures the camera getting a clear image even in complete darkness.
- Features AI multi-object detection and tracking, which can constantly track one of the persons and vehicles intelligently identified in the image.
- Low-profile spherical shape and 3-axis nonorthogonal mechanical stabilized structure, minimize the gyration radius and the wind resistance of the pod. The gimbal is able to spin continually around its yaw axis.
- Supports network, UART and S.BUS control and compatible with both private protocol and MAVLink protocol.
- Thanks to the Dual-IMU complementary algorithms with IMU temperature control and carrier AHRS fusion, the gimbal provides a stabilization accuracy at $\pm 0.01^\circ$.
- Can be mounted onto multiple carriers, whether downward or upward.
- With the Dragonfly software, user can watch the image and control the pod without protocol ducking, and download photos and videos online as well.
- With the XF-QGC software, all the functions of the pod can be achieved in conjunction with an open source autopilot.
- Screen supports overlaying OSD information. Image supports EXIF saving. Live video

stream and recording supports SEI saving.(The SEI functionality will be supported via subsequent firmware updates)

· 20~53 VDC wide voltage input.

Specifications

| General | | |
|--------------------------------|---|--|
| Product Name | D-80N | |
| Dimensions | 89.6 x 86 x 124.6mm | |
| Weight | 398g | |
| Operating Voltage | 20 ~ 53 VDC | |
| Power | 6.5W (AVG) / 28.2W (Stall, lighting on) | |
| Mounting | Downward / Upward | |
| Gimbal | | |
| Gimbal Type | 3-axis Nonorthogonal Mechanical Stabilization | |
| Angular Accuracy | ±0.01° | |
| Max Stable Tilt Angle | 45° | |
| Controllable Range | Pitch:-145° ~ +60°, Yaw: ±360°constantly | |
| Max Controllable Speed | 150°/s | |
| Zoom Camera | | |
| Image Sensor | 1/2.8-inch CMOS; Effective Pixels: 2.07M | |
| Lens | Focal Length: 6.1~61.4mm (Equivalent focal length: 41.6~415.8mm) Aperture: f/1.8~f/2.6 HFOV: 48.8° ~ 5.2° VFOV: 28.6° ~ 2.9° DFOV: 55.0° ~ 6.0° | |
| Resolution | 1920(H) x 1080(V) | |
| Pixel Pitch | 2.9μm(H) x 2.9μm(V) | |
| Optical Zoom Rate | 10x | |
| Equivalent Digital Zoom Rate | 4x | |
| Object Detection Distance | EN62676-4:2015 | Person ^[1] : 927m Light vehicle ^[2] : 1218m Large vehicle ^[3] : 2595m |
| | Johnson Criteria | Person: 10586m Light vehicle: 32464m Large vehicle: 69163m |
| Object Identification Distance | EN62676-4:2015 | Person: 185m Light vehicle: 244m Large vehicle: 519m |
| | Johnson Criteria | Person: 2647m Light vehicle: 8116m Large vehicle: 17291m |

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|--------------------------------------|---|---|
| Object Verification Distance | EN62676-4:2015 | Person: 93m Light vehicle: 122m Large vehicle: 260m |
| | Johnson Criteria | Person: 1323m Light vehicle: 4058m Large vehicle: 8646m |
| Laser Lighting Module | | |
| Wavelength | 850±10nm | |
| Laser Power | 0.8W | |
| Beam Angle | 8° | |
| Beam Diameter | 14m @ 100m | |
| Effective Illumination Distance | ≤200m | |
| Laser Safety | Class 3B (IEC 60825-1:2014) | |
| AI Multi-object Detection & Tracking | | |
| Object Size | 16 x 16 ~ 128 x 128 px | |
| Object Identification Delay | < 40ms | |
| Tracking Speed | ±32 px / field | |
| Tracking Deviation Refresh Rate | 30Hz | |
| Tracking Deviation Output Delay | ≤5ms | |
| Image & Video | | |
| Image Format | JPEG | |
| Maximum Image Resolution | 1920 x 1080 | |
| Video Format | MP4 | |
| Maximum Video Resolution | Stream:1920 x 1080 @30fps Recording: 1920 x 1080 @30fps | |
| OSD | Time, Camera attitude, Carrier coordinate, Zoom rate,Storage status | |
| EXIF | Time, Camera attitude, Carrier coordinate, Resolution | |
| SEI | Refer to User Manual | |
| Stream Encode Format | H.264, H.265 | |
| Stream Network Protocol | RTSP | |
| Average Stream Delay & FPS[4] | OSD OFF & target detection OFF | Dragonfly: 190ms QGC: 230ms FPS: 30 |
| | OSD ON & target detection OFF | Dragonfly: 190ms QGC: 240ms FPS: 30 |

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|-----------------------|--|---|
| | OSD OFF & target detection ON | Dragonfly: 200ms QGC: 240ms FPS: 30 |
| | OSD ON & target detection ON | Dragonfly: 200ms QGC: 250ms FPS: 30 |
| Storage | | |
| Supported SD Cards | Supports a U3/V30 or above MicroSD card with a capacity of up to 256GB | |
| Environment | | |
| Operating Temperature | -20°C ~ 50°C | |
| Storage Temperature | -40°C ~ 60°C | |
| Operating Humidity | ≤85%RH (Non-condensing) | |

[1] Reference dimension of person: 1.8x0.5m. Critical dimension under Johnson criteria is 0.75m.

[2] Reference dimension of light vehicle: 4.2x1.8m. Critical dimension under Johnson criteria is 2.3m.

[3] Reference dimension of large vehicle: 6.0x4.0m. Critical dimension under Johnson criteria is 4.9m.

[4] Measured with the pod directly wired to a computer at 1x zoom ratio. When the zoom ratio exceeds 10x, video stream delay will increase and frame rates will decrease.