D-90AI Intelligent Multi-sensor Spherical Pod



Characteristics

- Features AI multi-object detection and tracking, which can constantly track one of the persons and vehicles intelligently identified in the image.
- Carries a 30x hybrid zoom camera, a thermal camera and a laser range finder.
- Low-profile spherical shape and 3-axis nonorthogonal mechanical stabilized structure, minimize the gyration radius and the wind resistance of the pod. The D-90DE is able to spin continually around its yaw axis.
- With the GCU, the D-90DE supports network, UART and S.BUS control. The GCU supports both private protocol and MAVLink protocol.
- Thanks to the Dual-IMU complementary algorithms with IMU temperature control and carrier AHRS fusion, the D-90DE provides a stabilization accuracy at ±0.01°.
- Can be mounted onto multiple carriers, whether downward or upward.
- With the GCU and the Dragonfly software, user can watch the image and control the pod without protocol ducking.
- With the customized QGC software, all the functions of the pod can be achieved in conjunction with an open source autopilot.
- Screen supports overlaying OSD information such as latitude, longitude and altitude.
 Image supports shooting point coordinate EXIF save. Video stream supports SEI stacking.
- 14~53 VDC wide voltage input.

Specifications

General					
Product Name	D-90ai				
Dimensions	Pod: 96.4 x 96 x 147mm				
	GCU: 45.4 x 40 x 13.5mm				
Weight	Pod: 608g				
	GCU: 18.6g				
Operating Voltage	14 ~ 53 VDC				
Power	Pod: 10.5W (AVG, ranging off) / 55W (Stall, ranging on)				
	GCU: 1.8W				
Mounting	Downward / Upwar			Harianal Bistones 105m	
Target Positioning Accuracy ^[1]	Horizonal Error: 1.8 Vertical Error: 0.7m		@	Horizonal Distance: 105m Relative Height: 75m	
	Horizonal Error: 17			Horizonal Distance: 513m	
	Vertical Error: 6.7m	- 	@	Relative Height: 119m	
	Horizonal Error: 33	.8m	@	Horizonal Distance: 1003m	
	Vertical Error: 13.7r	n	<u> </u>	Relative Height: 246m	
Gimbal					
Gimbal Type	3-axis Nonorthogonal Mechanical Stabilization				
Angular Accuracy	±0.01°				
Controllable Range	Pitch: -150 $^{\circ}$ \sim +50 $^{\circ}$, Yaw: $\pm 360 ^{\circ}$ constantly				
Max Controllable Speed	Pitch: ±200°/s, Yaw: ±200°/s				
Zoom Camera					
Image Sensor	1/2.8" CMOS; Effective Pixels: 2.07M				
Lens	Focal Length: $4.7 \sim 47 \text{mm}$ HFOV: $61.3^{\circ} \sim 6.8^{\circ}$				
Lens	VFOV: $36.9^{\circ} \sim 3.9^{\circ}$ DFOV: $68.4^{\circ} \sim 7.8^{\circ}$				
Resolution	1920 x 1080				
Pixel Pitch	2.9µm				
Optical Zoom Rate	10x				
Equivalent Digital Zoom Rate	3x				
Min Illumination	Night Vision off: 0.01Lux / F1.6				
	Night Vision on: 0.0015Lux / F1.6				
Object Detection Distance	EN62676-4:2015 Person ^[2] : 709m; Light vehicle ^[3] : 932m; Large vehicle ^[4] : 1986m				
	Johnson Criteria Person: 8103m; Light vehicle: 24851m; Large vehicle: 52943m				
Object Identification Distance	EN62676-4:2015 Johnson Criteria		•	cle: 187m; Large vehicle: 397m nicle: 6213m; Large vehicle: 13236m	
Object Verification Distance	EN62676-4:2015 Johnson Criteria		_	le: 93m; Large vehicle: 199m nicle: 3106m; Large vehicle: 6618m	

- [1] Measured by pod mounted on a dual antenna RTK positioned multicopter drone to a known coordinate point. The target positioning accuracy is influenced by carrier's positioning and orientation accuracy, angle between the direction of pod mounted and the heading of carrier, slant range, gradient of measurement line and air quality. The data is for reference only.
- [2] Reference dimension of person: 1.8x0.5m. Critical dimension under Johnson criteria is 0.75m
- [3] Reference dimension of light vehicle: 4.2x1.8m. Critical dimension under Johnson criteria is 2.3m
- [4] Reference dimension of large vehicle: 6.0x4.0m. Critical dimension under Johnson criteria is 4.9m

Thermal Sensor	Uncooled VOx Micro	bolometer		
memar sensor	Focal Length: 18mm			
	HFOV: 24°			
Lens				
	VFOV: 18° DFOV: 30.4°			
Resolution	640 x 512			
	12μm			
Pixel Pitch	8~12μm			
Spectral Band	o~12µ11 <50mk@25℃			
Sensitivity (NETD)	<50111k@25 C	Person, 750m; Light vehicle, 2200m; Large vehicle, 400		
Object Detection Distance	lahmaan Critaria	Person: 750m; Light vehicle: 2300m; Large vehicle: 490		
Object Identification Distance	Johnson Criteria	Person: 188m; Light vehicle: 575m; Large vehicle: 122		
Object Verification Distance		Person: 94m; Light vehicle: 288m; Large vehicle: 613n		
Laser Range Finder				
Wavelength	905nm			
Max Laser Power	1mW			
Beam Angle	3.5mrad			
Beam Diameter	0.35m @ 100m			
Laser Safety	Class 1M (IEC 60825-1:2014)			
Measurement Accuracy	±1.0m			
Measurement Range	5-1200m (φ12m vertical surface with 20% reflectivity)			
AI Multi-object Detection &	ጿ Tracking			
Object Size	16x16 ~ 128x128 px			
Object Identification Delay	<40ms			
Tracking Speed	\pm 32 px / field			
Tracking Deviation Refresh Rate	30Hz			
Tracking Deviation Output Delay	≤5ms			
Image & Video				
Image Format	JPEG			
Maximum Image Resolution	1920 x 1080			
EXIF	Shooting point coord	dinate		
Video Format	MP4			
Maximum Video Resolution	1080P@25fps			
Stream Encode Format	H.264, H.265			
Stream Network Protocol	RTSP			
Storage				
Supported SD Cards	Supports a Speed Class 10 MicroSD card with a capacity of up to 256GB			
Support File System	HDD-FAT32			
Environment				
Operating Temperature	-20°C ~ 50°C			
Storage Temperature	-40°C ~ 60°C			
Operating Humidity	≤85%RH (Non-condensing)			