Z-6N

Intelligent Black Light Full-Color Night Vision Pod



Characteristics

- 120x hybrid zoom camera, combined with the 1/1.8-inch ultra-starlight image sensor and AI-ISP full-color night vision imaging engine, can present clear full-color images in extremely low-light environments, delivering night vision-level low-light imaging experience. The Z-6N also features AI-HDR, ensuring both highlights and shadow details remain clearly visible even in complex lighting environments with strong contrast between bright and dark areas.
- Features AI multi-object detection and tracking, which can constantly track one of the persons and vehicles intelligently identified in the image.
- 3-axis orthogonal mechanical stabilized structure. The gimbal is able to spin continually around its yaw axis.
- Supports network, UART and S.BUS control and compatible with both private protocol and MAVLink protocol.
- Thanks to the Dual-IMU complementary algorithms with IMU temperature control and carrier AHRS fusion, the gimbal provides a stabilization accuracy at ±0.01°.
- Can be mounted onto multiple carriers, whether downward or upward.
- With the Dragonfly software, user can watch the image and control the pod without protocol ducking, and download photos and videos online as well.
- With the customized QGC software, all the functions of the pod can be achieved in conjunction with an open source autopilot.
- Screen supports overlaying OSD information. Image supports EXIF saving. Live video stream and recording supports SEI saving.
- 20~53 VDC wide voltage input.

Specifications

General			
Product Name	Z-6N		
Dimensions	141 x 98 x 160mm		
Weight	670g		
Operating Voltage	20 ~ 53 VDC		
Power	5W (AVG) / 75W (Stall)		
Mounting	Downward / Upward		
Gimbal			
Gimbal Type	3-axis Orthogonal Mechanical Stabilization		
Angular Accuracy	±0.01°		
Controllable Range	Pitch: $\pm 135^{\circ}$, Roll: $\pm 85^{\circ}$, Yaw: $\pm 360^{\circ}$ constantly		
Max Controllable Speed	\pm 200°/s		
Zoom Camera			
Image Sensor	1/1.8-inch CMOS; Effective Pixels: 4.09M		
Lens	Focal Length: 7.3~146.6mm (Equivalent focal length: 35.4~708.5mm) Aperture: f/1.6~f/4.1 HFOV: $56.0^\circ \sim 3.0^\circ$ VFOV: $33.5^\circ \sim 1.7^\circ$ DFOV: $62.8^\circ \sim 3.5^\circ$		
Resolution	2688(H) x 1520(V)		
Pixel Pitch	2.9μm(H) x 2.9μm(V)		
Optical Zoom Rate	20x		
Equivalent Digital Zoom Rate	6x		
Object Detection Distance	EN62676-4:2015 Johnson Criteria	Person ^[1] : 2213m; Light vehicle ^[2] : 2908m; Large vehicle ^[3] : 6196m Person: 25276m; Light vehicle: 77513m; Large vehicle: 165136m	
Object Identification Distance	EN62676-4:2015 Johnson Criteria	Person: 443m; Light vehicle: 582m; Large vehicle: 1239m Person: 6319m; Light vehicle: 19378m; Large vehicle: 41284m	
Object Verification Distance	EN62676-4:2015 Johnson Criteria	Person: 221m; Light vehicle: 291m; Large vehicle: 620m Person: 3160m; Light vehicle: 9689m; Large vehicle: 20642m	
AI Multi-object Detection 8	ያ Tracking		
Object Size	16x16 ~ 128x128 px		
Object Identification Delay	< 40ms		
Tracking Speed	±32 px / field		
Tracking Deviation Refresh Rate	30Hz		
Tracking Deviation Output Delay	≤5ms		

- [1] Reference dimension of person: 1.8x0.5m. Critical dimension under Johnson criteria is 0.75m
- [2] Reference dimension of light vehicle: 4.2x1.8m. Critical dimension under Johnson criteria is 2.3m
- [3] Reference dimension of large vehicle: 6.0x4.0m. Critical dimension under Johnson criteria is 4.9m

Image & Video		
Image Format	JPEG	
Maximum Image Resolution	2688 x 1520	
Video Format	MP4	
Maximum Video Resolution	Stream: 2688 x 1520 @30fps Recording: 2688 x 1520 @30fps	
OSD	Time, Camera attitude, Carrier coordinate, Zoom rate, Storage status	
EXIF	Time, Camera attitude, Carrier coordinate, Resolution	
SEI	Refer to User Manual	
Stream Encode Format	H.264 , H.265	
Stream Network Protocol	RTSP	
Storage		
Supported SD Cards	Supports a U3/V30 or above MicroSD card with a capacity of up to 256GB	
Environment		
Operating Temperature	-20°C ~ 50°C	
Storage Temperature	-40°C ~ 60°C	
Operating Humidity	≤85%RH (Non-condensing)	